

Date
26/07/19

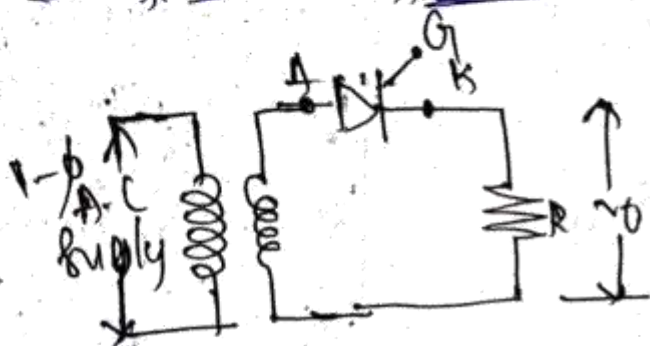
UNIT - II

Single Phase Controlled Converters (AC-DC)

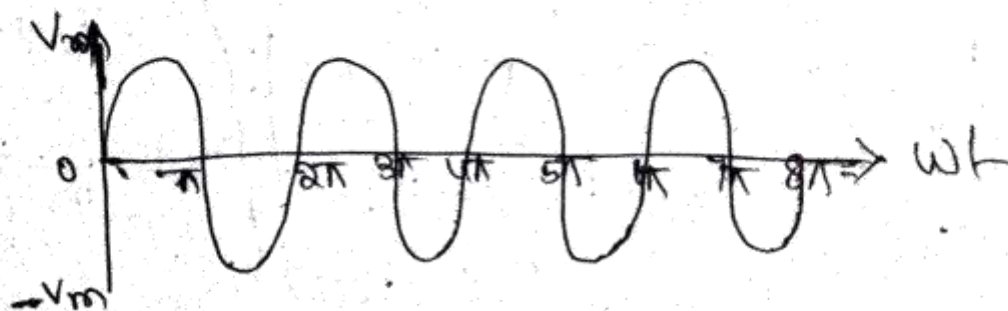
- It always single phase AC voltage
- that AC voltage is converted into ^{average} D.C.
- Single phase AC converted to DC, that is mainly two parts

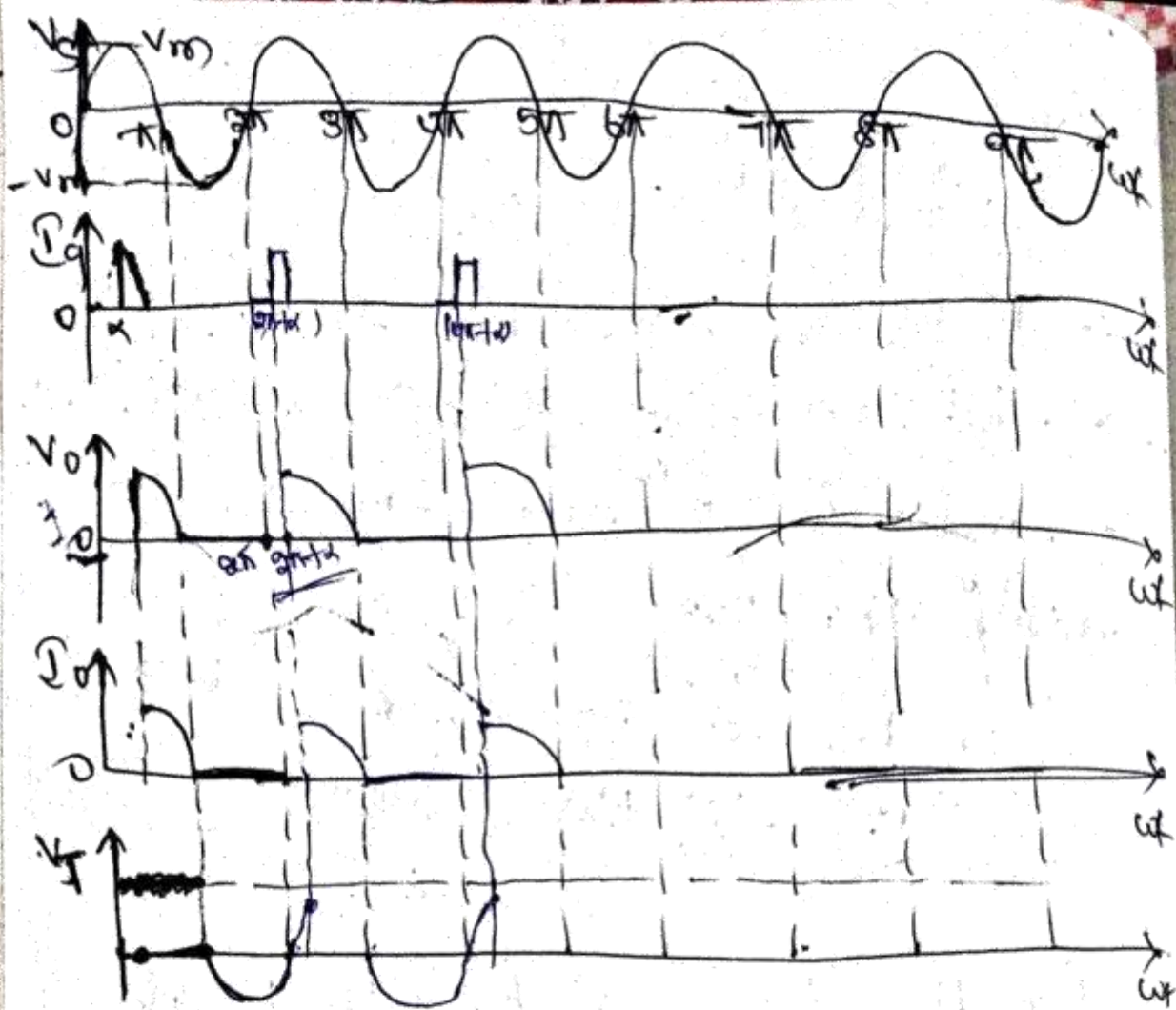
- (i) 1- ϕ half wave converter - low power application
- (ii) 1- ϕ full wave converter - full power application

(i) 1- ϕ Half wave Converter With "R" Load :-



1. All the SCR's are treated as ideal devices
2. We have to assume Gate signal is present for the device.





→ It gives more o/p voltage [firing angle]

$$V_o = \frac{1}{2\pi} \int_{\alpha}^{\pi} V_s d\omega t$$

$$V_s = V_m \sin \omega t$$

$$= \frac{1}{2\pi} \int_{\alpha}^{\pi} V_m \sin \omega t d\omega t$$

$$= \frac{V_m}{2\pi} \left[-\cos \omega t \right]_{\alpha}^{\pi}$$

$$V_o = \frac{V_m}{2\pi} (1 + \cos \alpha)$$

From (or) Average of p

$$V_o = \frac{1}{2\pi} \int_{\alpha}^{\pi} V_m \sin \omega t d\omega t$$

RMS value,

$$V_{rms} = \left[\frac{1}{2\pi} \int_{\alpha}^{\pi} V_m^2 \sin^2 \omega t d\omega t \right]^{1/2}$$

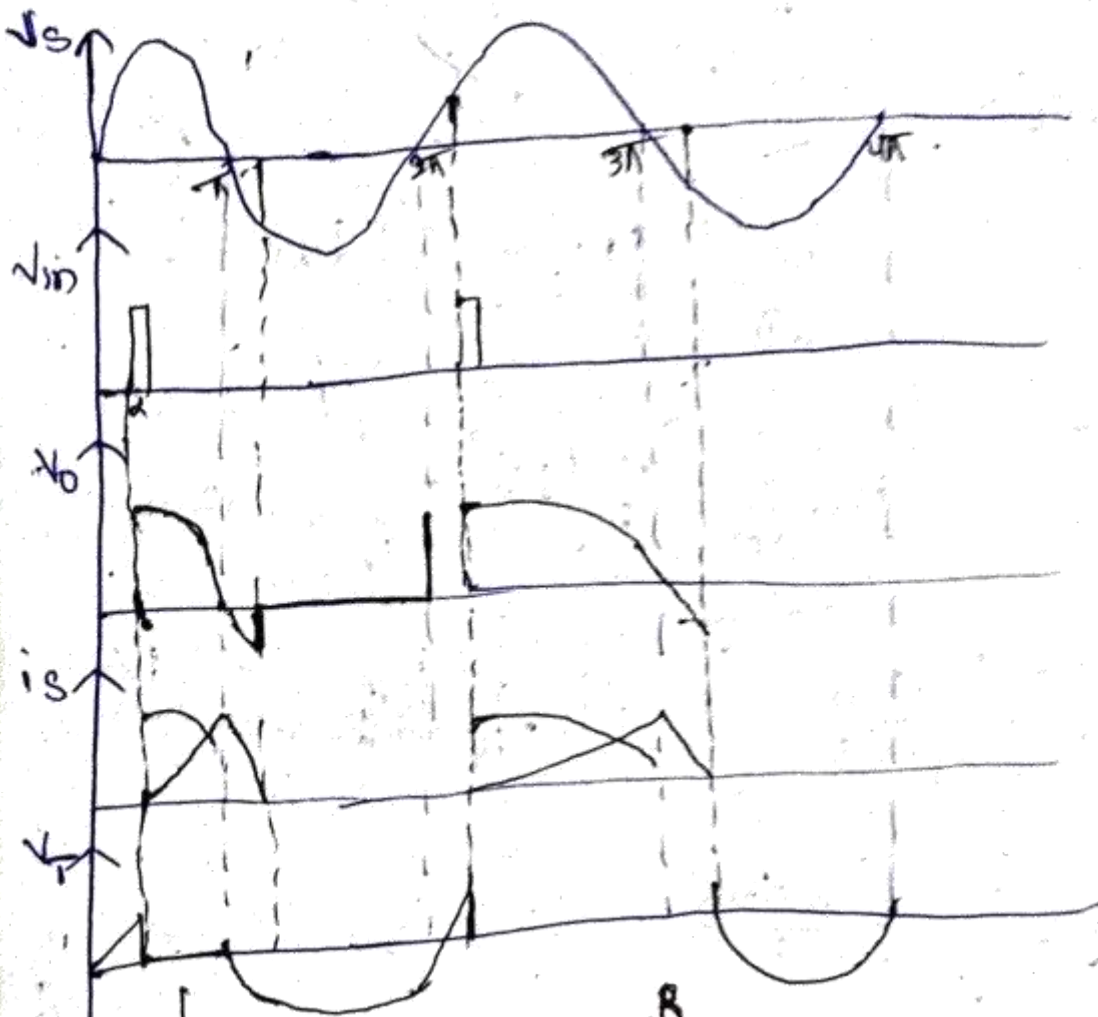
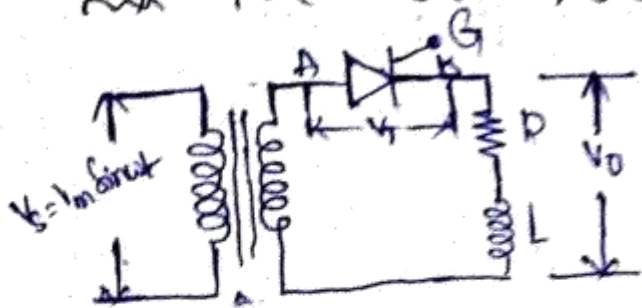
$$= \frac{V_m}{2\pi} \left[\int_{\alpha}^{\pi} \frac{1 - \cos 2\omega t}{2} d\omega t \right]^{1/2}$$

$$= \frac{V_m}{2\pi} \left[\int_{\alpha}^{\pi} d\omega t - \frac{1}{2} \sin 2\omega t \right]^{1/2}$$

$$V_{rms} = \frac{V_m}{2\pi} (\pi - \alpha - \frac{1}{2} \sin 2\omega)$$

→ $\sin 2\pi = 0$

* 1- ϕ half wave Rectifier with R-L load:-



$$V_o = \frac{1}{2\pi} \int_{\alpha}^{\beta} V_m \sin \omega t \, d\omega t$$

$$V_o = V_m \sin \omega t -$$

$$= \frac{V_m}{2\pi} \left[-\cos \omega t \right]_{\alpha}^{\beta}$$

$$V_o = \frac{V_m}{2\pi} (\cos \alpha - \cos \beta)$$

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$$i_0 = \frac{V_0}{R} = \frac{V_m}{2\pi R} (\cos\alpha - \cos\beta)$$

Mean (or) Average :-

$$\Rightarrow V_{rms} = \left[\frac{1}{2\pi} \int_{\alpha}^{\beta} V_m \sin\omega t \, d\omega t \right]$$

$$\sin\omega t = \frac{1 - \cos 2\omega t}{2}$$

$$= \frac{V_m}{2\pi} \int_{\alpha}^{\beta} \left(\frac{1 - \cos 2\omega t}{2} \right) d\omega t \quad \frac{1}{2}$$

$$= \frac{V_m}{2\pi} \left[\frac{1}{2} d\omega t - \int_{\alpha}^{\beta} \frac{\sin 2\omega t}{2} \right]$$

$$V_{rms} = \left[\frac{V_m}{4\pi} (B - \alpha) - \frac{1}{2} (\sin 2B - \sin 2\alpha) \right] \frac{1}{2}$$

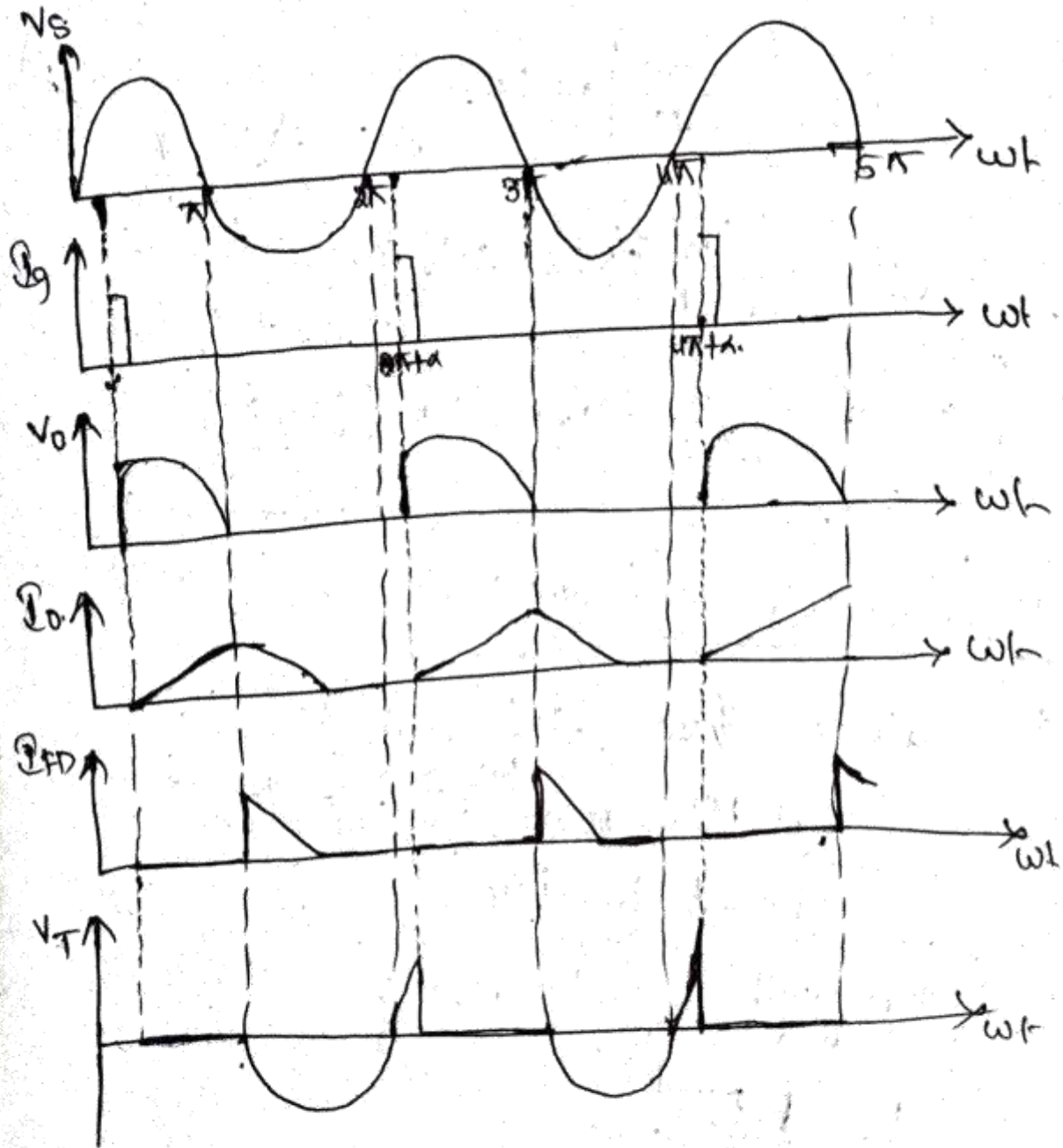
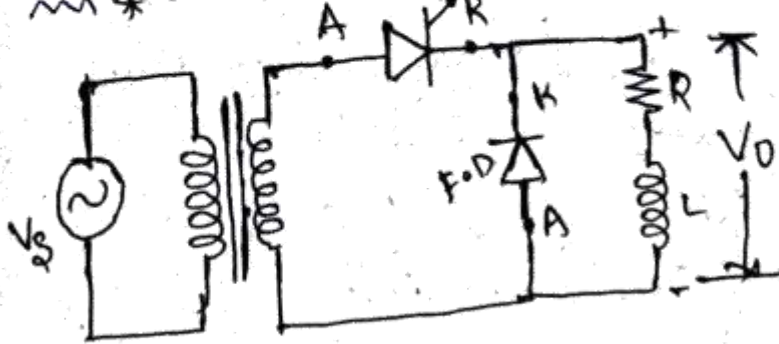
$$P_{rms} = \frac{V_0 R_{rms}}{R}$$

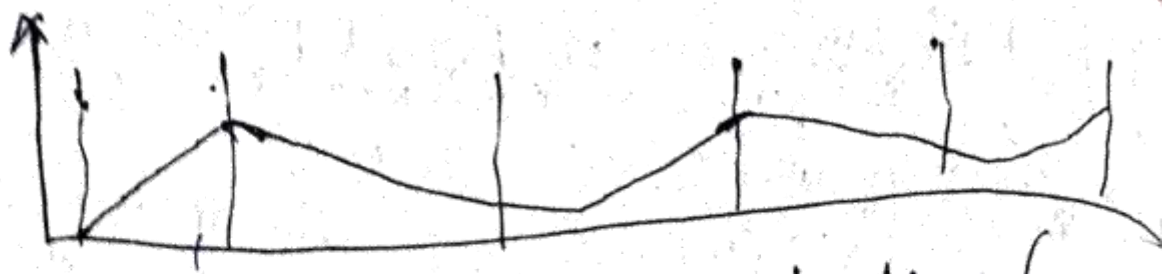
$$= \frac{1}{R} \left[\frac{V_m}{4\pi R} (B - \alpha) - \frac{1}{2} (\sin 2B - \sin 2\alpha) \right]$$


$$P_{rms} = \frac{V_m}{2\pi R} \left[(B - \alpha) - \frac{1}{2} (\sin 2B - \sin 2\alpha) \right]$$

* 1- ϕ Half wave Converter with R-L load and free wheeling diode :-

F.D :-
To improve efficiency, power factor.






Continuous Current Mode Wave form

$$V_o = \frac{1}{2\pi} \int_{\alpha}^{\pi} V_m \sin \omega t d\omega t$$

$$V_o = \frac{V_m}{2\pi} [1 + \cos \alpha]$$

$$PF = \frac{V_{orms}}{V_s}$$

$$V_{orms} = \left[\frac{V_m^2}{4\pi} (\pi - \alpha) + \frac{1}{2} \sin 2\alpha \right]^{1/2}$$

$$V_{orms} = \frac{V_m}{2\sqrt{2}\pi} \left[(\pi - \alpha) + \frac{1}{2} \sin 2\alpha \right]^{1/2}$$

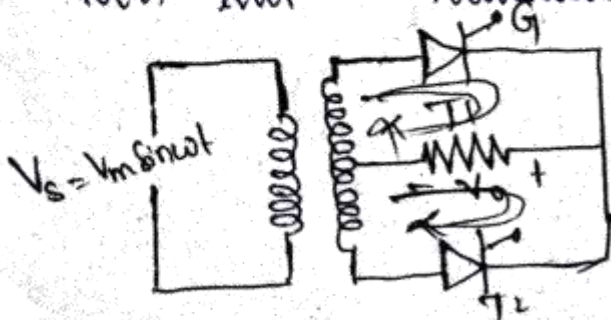
1- ϕ full wave Converter :-

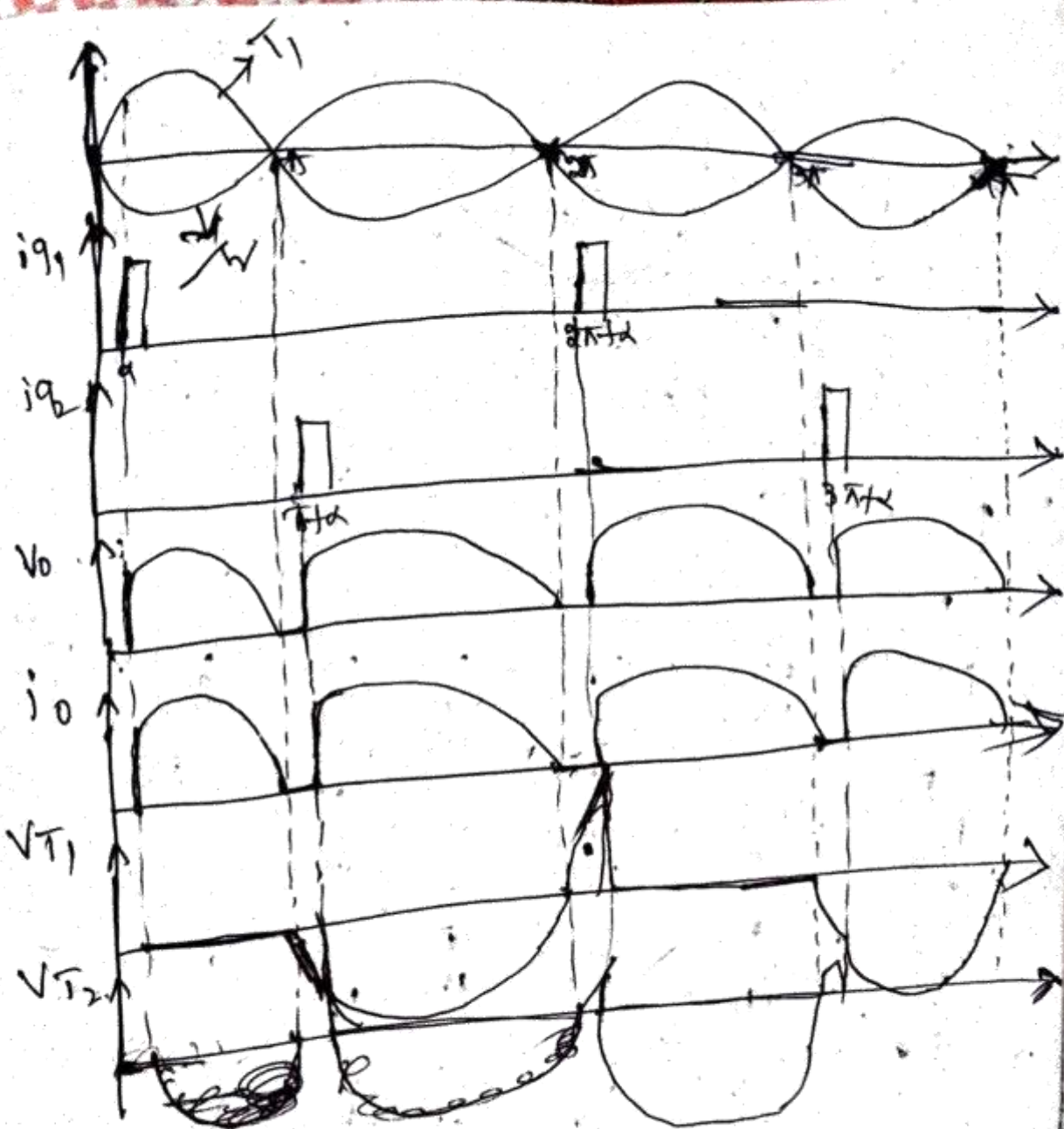
* mainly two types: ^{for centre-tapped}

(i) Mid point Configuration

(ii) Bridge type.

(i) Mid point Configuration :-





$$V_o = \frac{2}{2\pi} \int_{\alpha}^{\pi} V_m \sin \omega t \, d\omega t$$

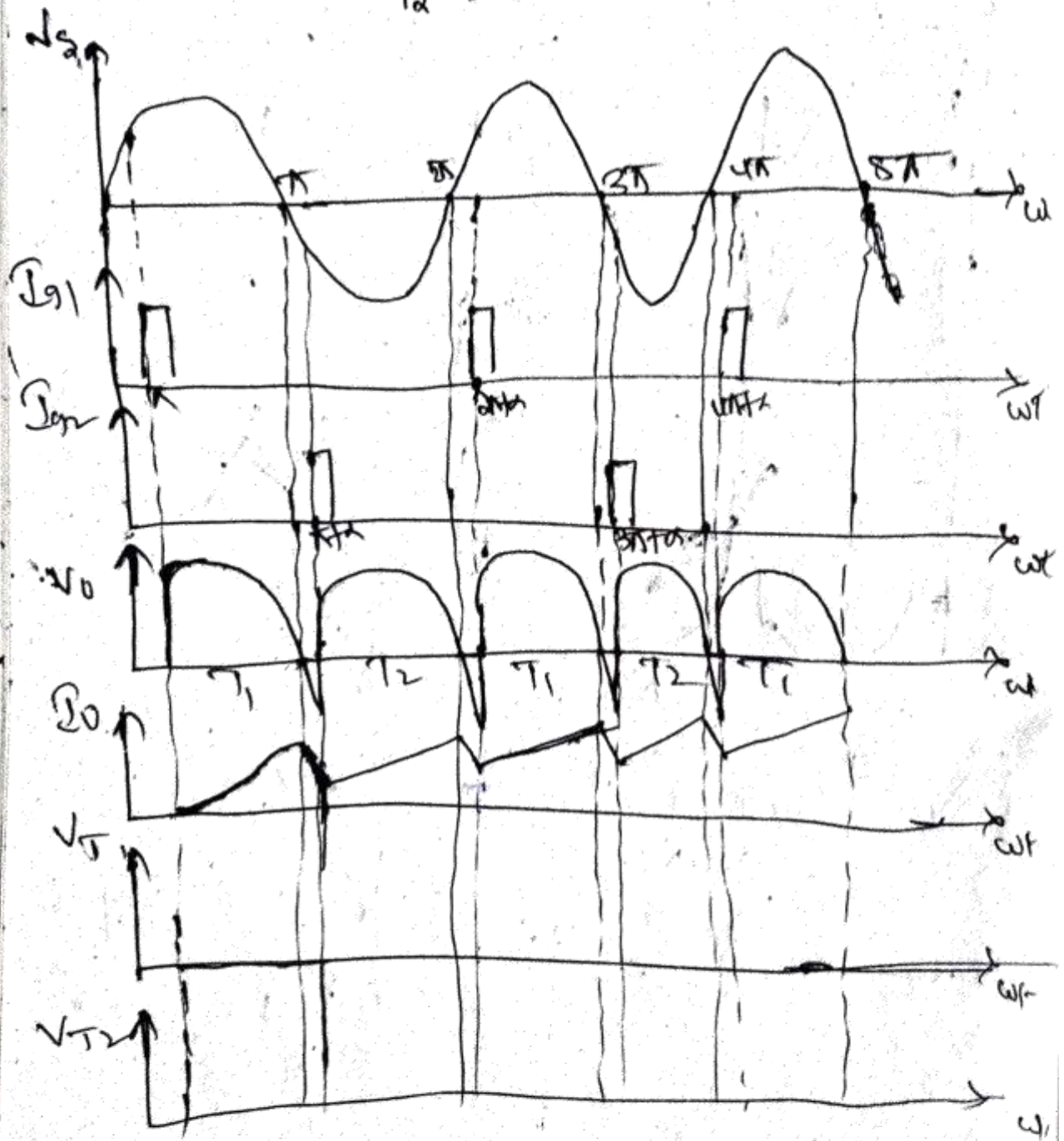
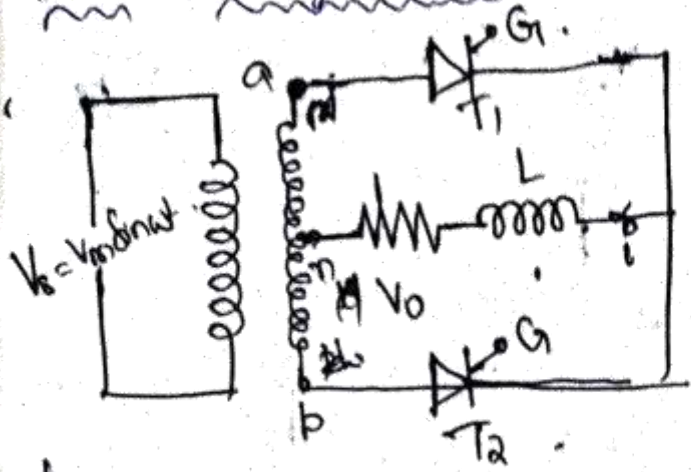
$$V_o = \frac{V_m}{\pi} (1 + \cos \alpha)$$

$$P_{oms} = \frac{V_{oms}}{R}$$

$$I_o = V_o / R$$

$$V_{oms} = \frac{V_m}{\sqrt{2\pi}} \left[(\pi - \alpha) + \frac{1}{2} \sin 2\alpha \right]^{1/2}$$

R-L Configuration :-



$$V_o = \frac{2}{2\pi} \int_{\alpha}^{\pi+\alpha} V_m \sin \omega t \, d \omega t$$

$$\begin{aligned}
 V_0 &= \frac{V_m}{\pi} \int_{\alpha}^{\pi+\alpha} \sin \omega t \, d\omega t \\
 &= \frac{V_m}{\pi} \left[-\cos \omega t \right]_{\alpha}^{\pi+\alpha} \\
 &= \frac{V_m}{\pi} \left[-\cos(\pi+\alpha) + \cos \alpha \right] \\
 &= \frac{V_m}{\pi} \left[\cos \alpha + (\cos \pi \cdot \cos \alpha - \sin \pi \cdot \sin \alpha) \right]
 \end{aligned}$$

$$V_0 = \frac{2V_m}{\pi} \cos \alpha$$

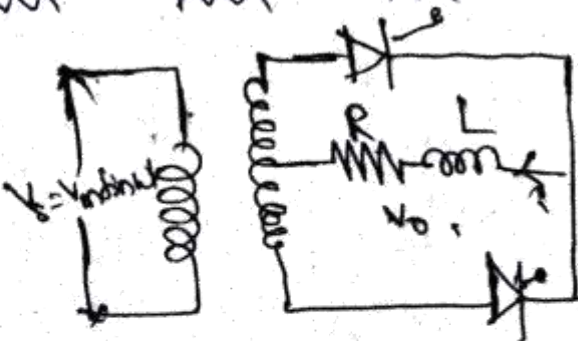
$$I_0 = \frac{V_0}{R}$$

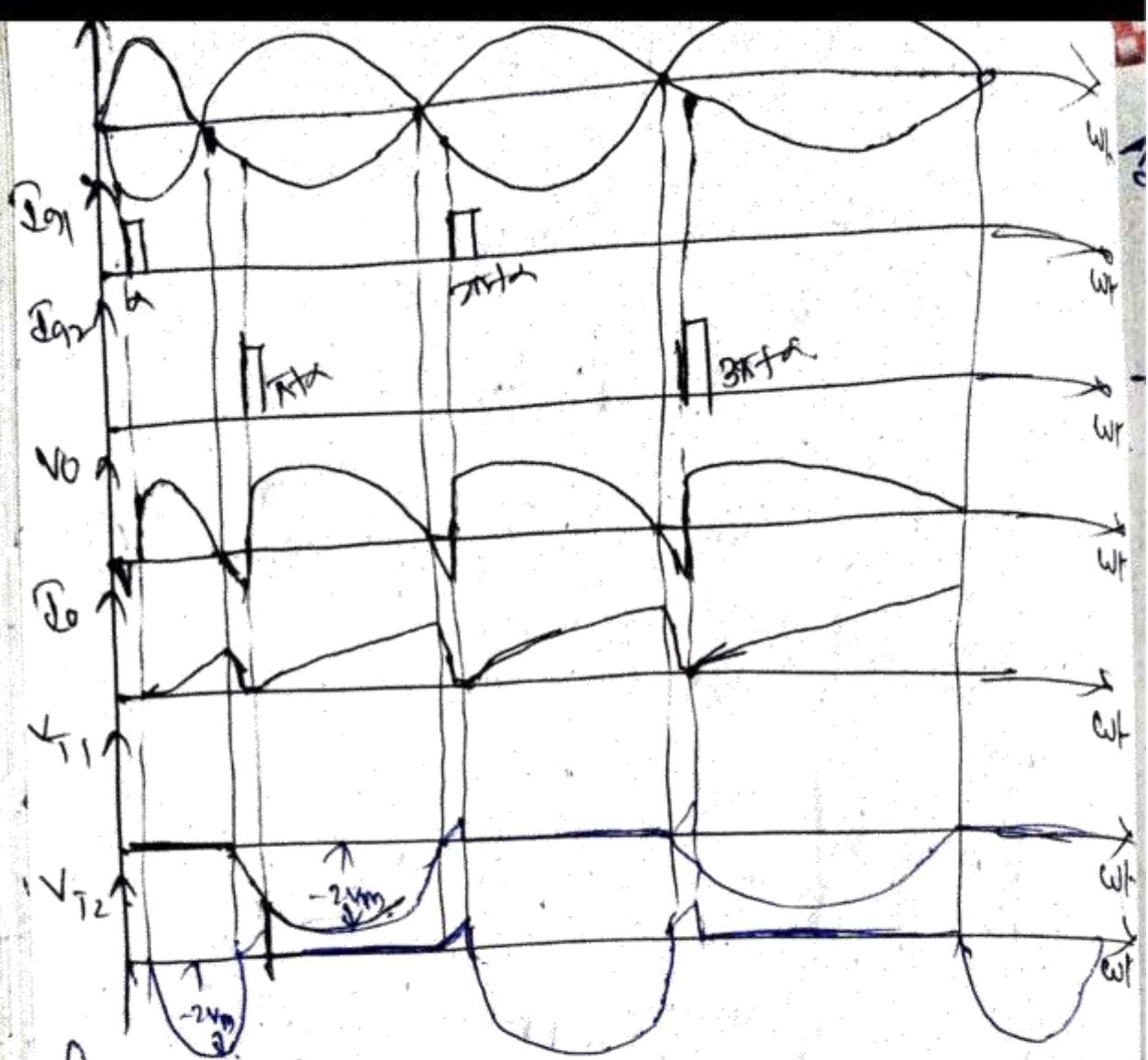
$$V_{rms} = \frac{V_m}{\sqrt{\pi}} \left(\pi \cos^2 \alpha + \frac{1}{2} \sin^2 \alpha \right)$$

$$I_{rms} = \frac{V_{rms}}{R}$$

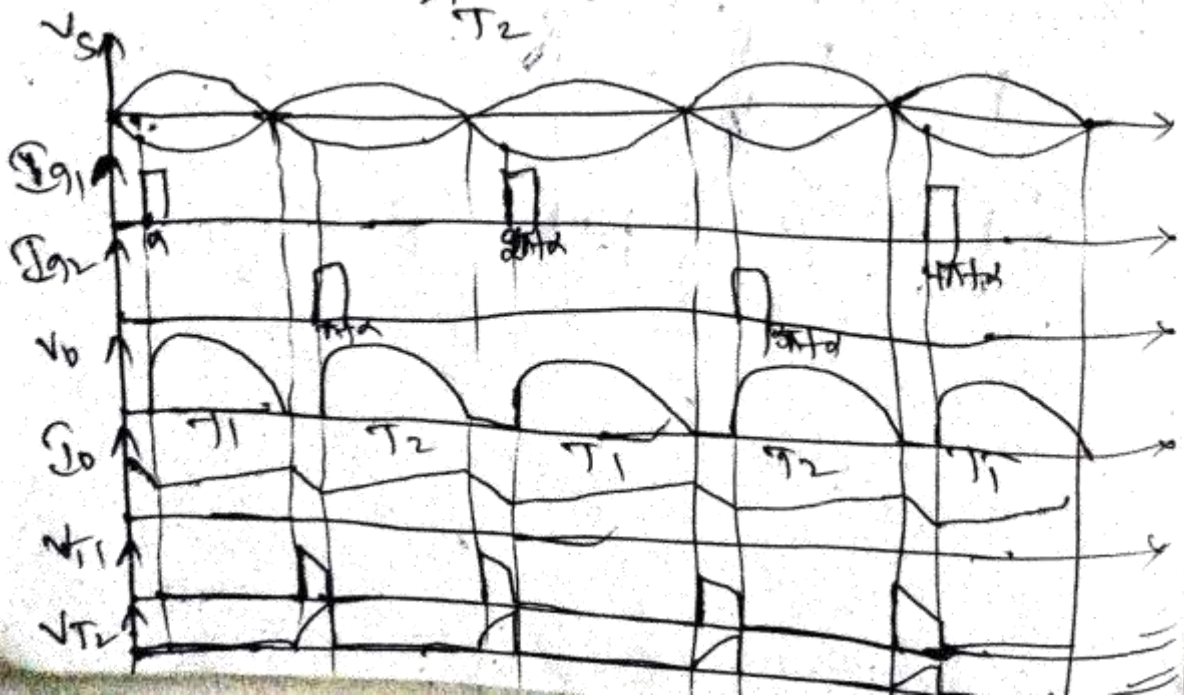
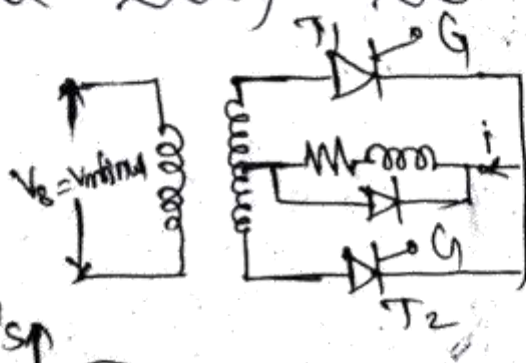
1- ϕ full wave

* R-L load and ~~resistor~~ inductor





Free-Wheeling Diode :-

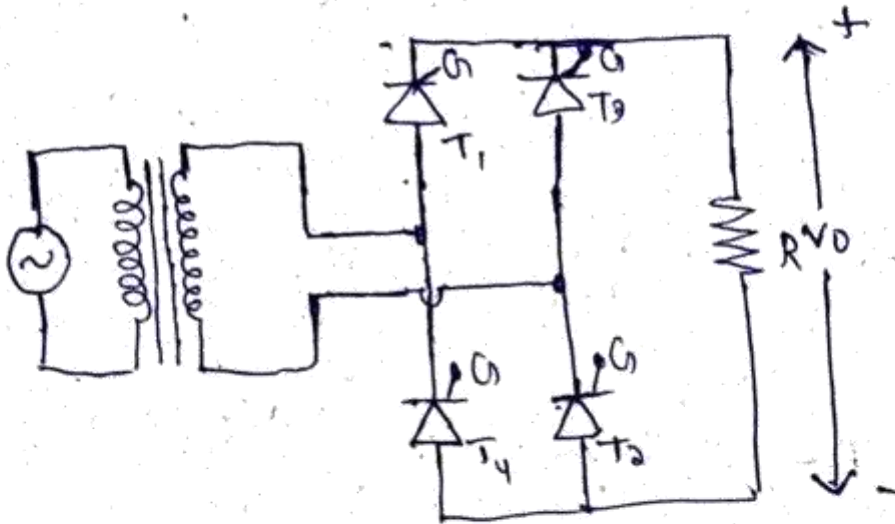


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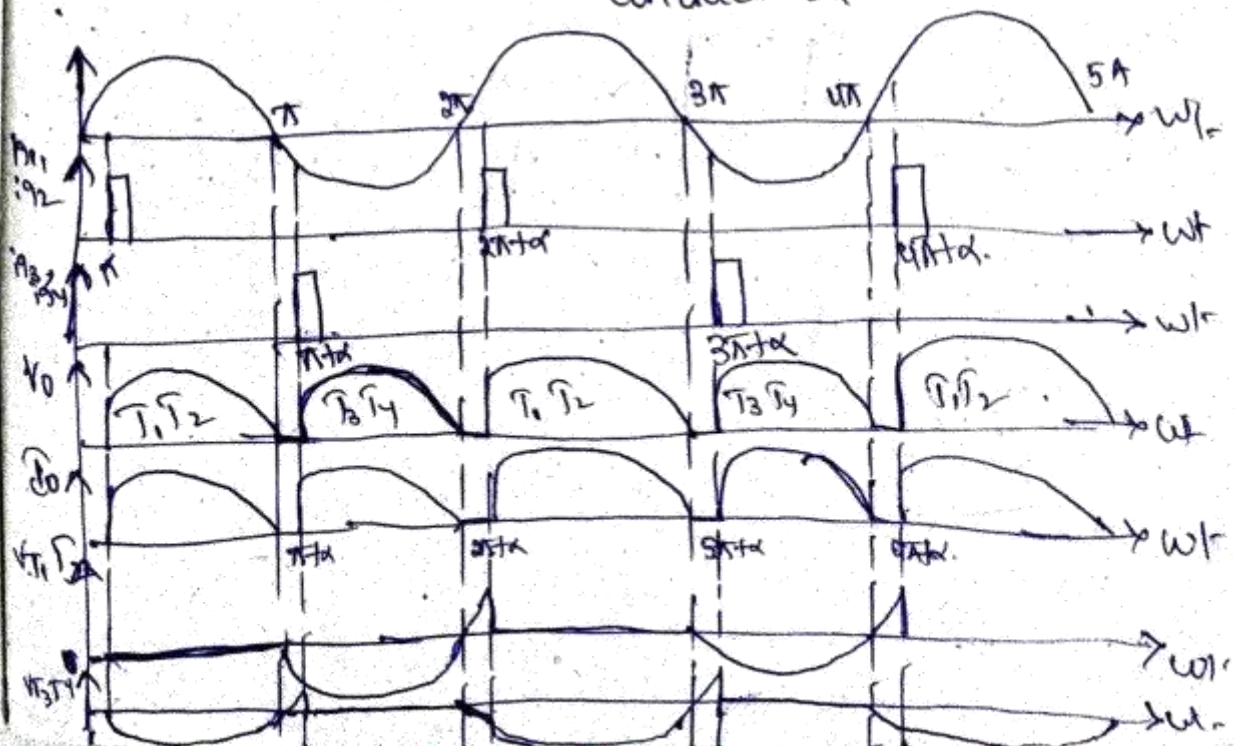
Bridge Configuration:-

→ The mid point Converter disadvantages are avoided by Bridge Converter.

Single phase Bridge Converter With R-Load:-



→ '0- π ' interval T_1, T_2 gets f.B and gets conduction
 • T_3, T_4 not at all comes to conduction



$$V_o = \frac{2}{2\pi} \int_0^{\pi} V_m \sin \omega t d\omega t$$

$$V_o = \frac{V_m}{\pi} [1 + \cos \alpha]$$

$$I_o = \frac{V_o}{R}$$

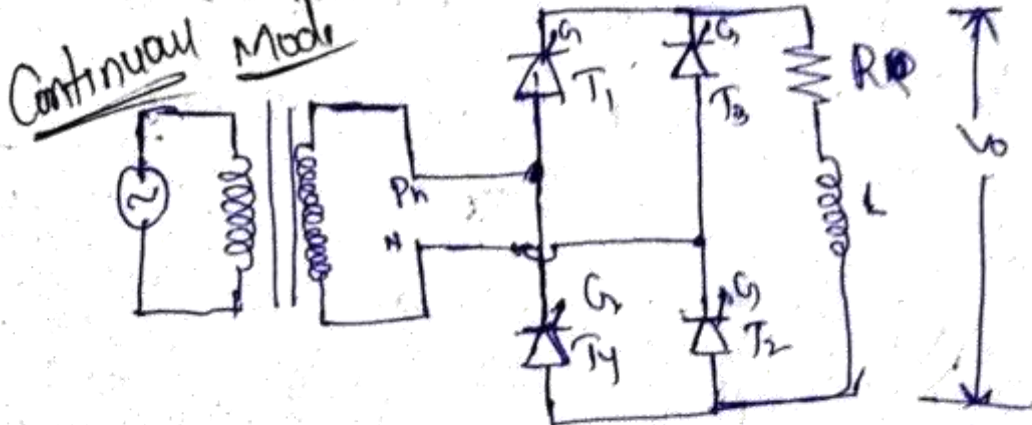
$$V_o = \frac{V_m}{\pi R} [1 + \cos \alpha]$$

$$\Rightarrow V_{rms} = \frac{2}{2\pi} \int_0^{\pi} [V_m \sin \omega t d\omega t]^{\frac{1}{2}}$$

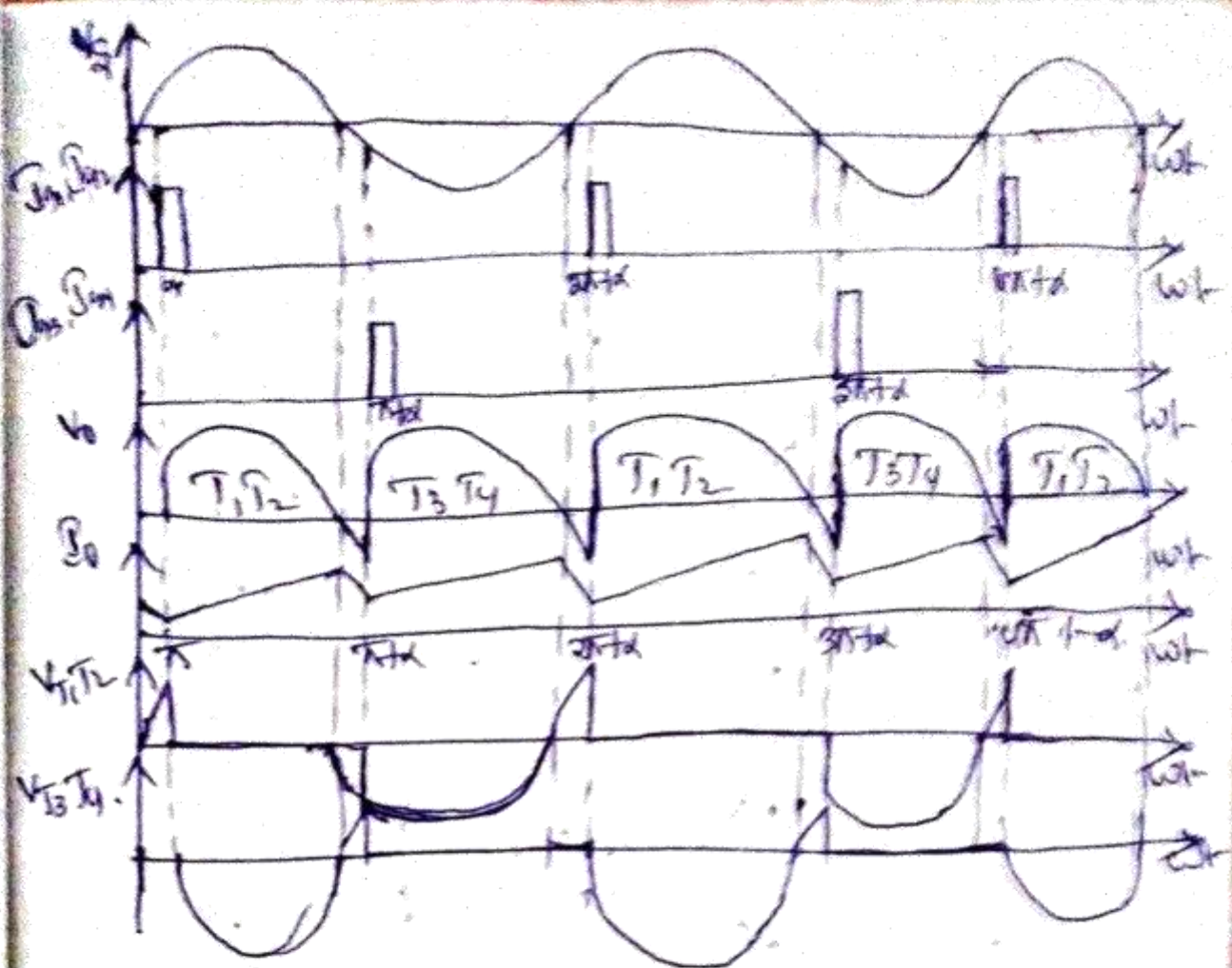
$$= \frac{V_m}{\sqrt{2\pi}} \left[(\pi - \alpha) + \frac{1}{2} \sin 2\omega t \right]^{\frac{1}{2}}$$

$$I_{rms} = \frac{V_{rms}}{R} = \frac{V_m}{\sqrt{2\pi} R} \left[(\pi - \alpha) + \frac{1}{2} \sin 2\omega t \right]^{\frac{1}{2}}$$

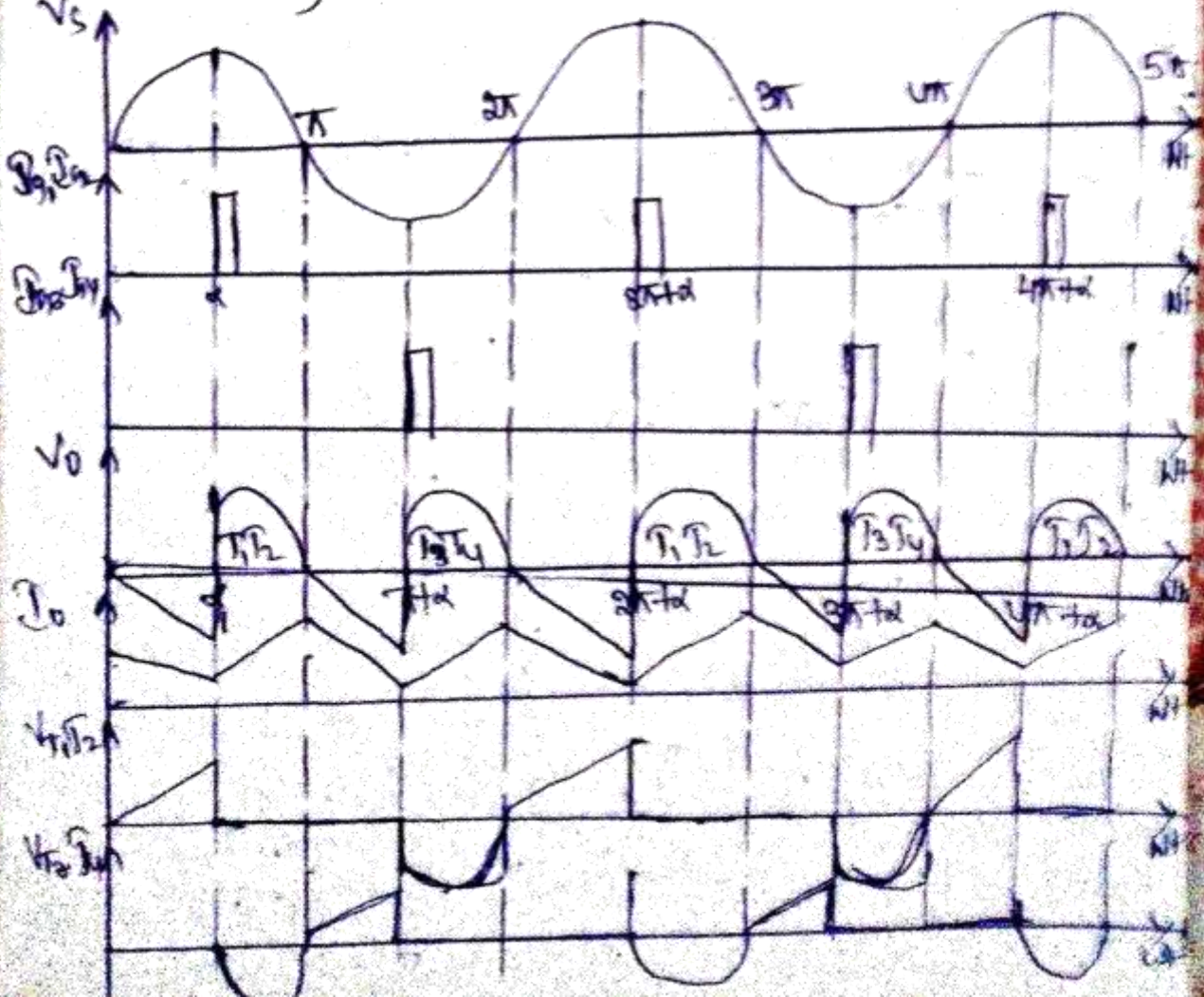
* Single phase Bridge Converter with R-L load



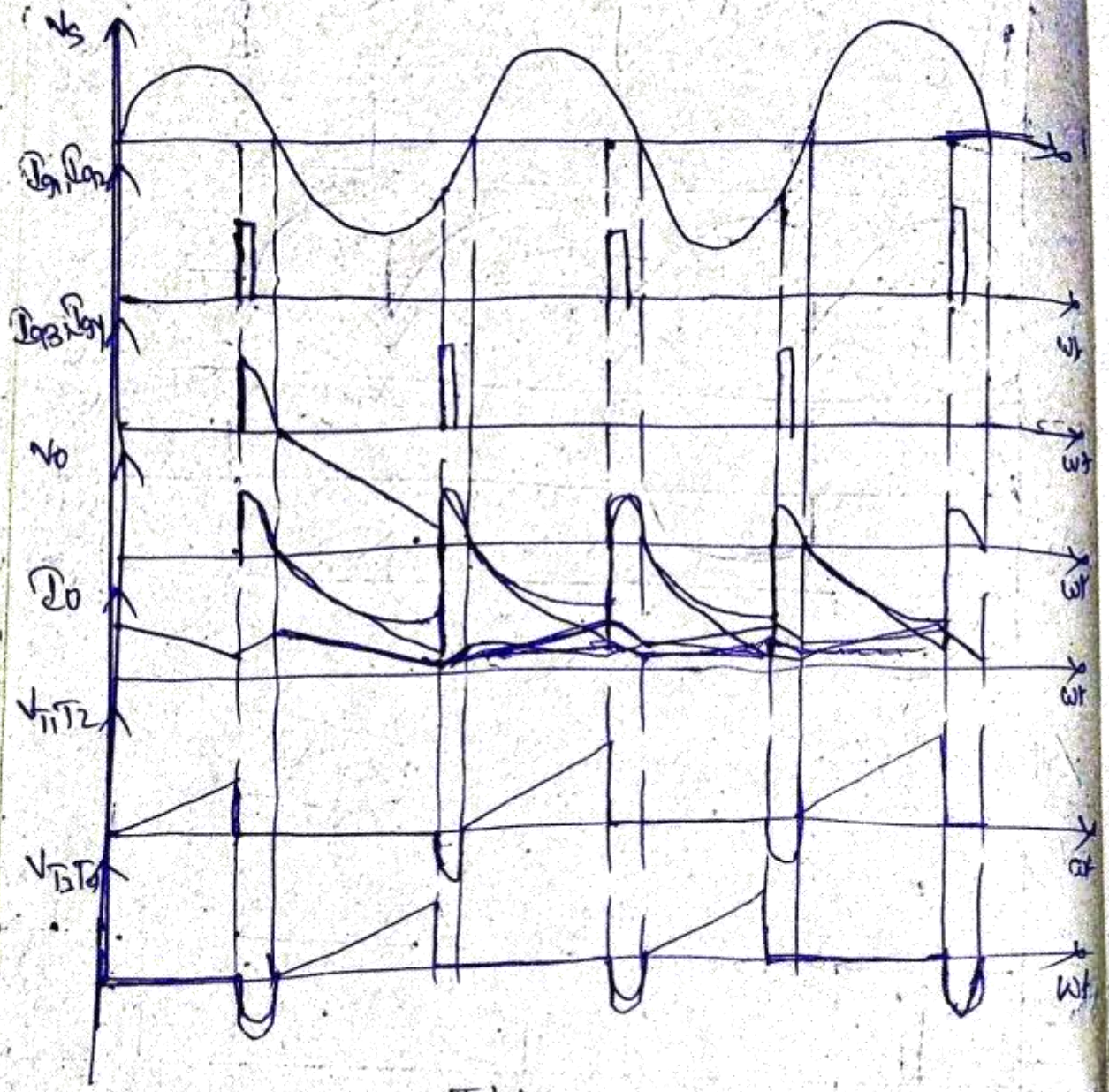
Same



At firing angle 90° $\alpha = \frac{\pi}{2}$



At firing angle $\alpha = 150^\circ$



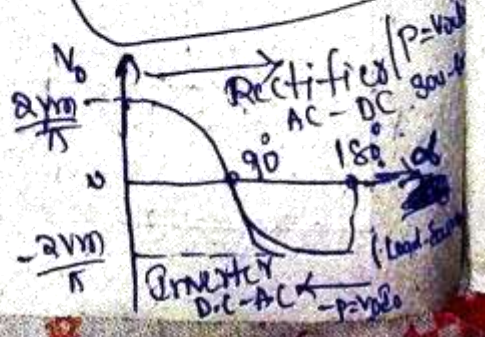
$$V_o = \frac{2}{2\pi} \int_{\alpha}^{\pi+\alpha} V_m \sin \omega t \, d\omega t$$

$$V_o = \frac{2 V_m}{\pi} \cos \alpha$$

$$I_o = \frac{V_o}{R}$$

$$I_o = \frac{2 V_m}{\pi R} \cos \alpha$$

$$\begin{aligned} V_o = \frac{2V_m}{\pi} &\Rightarrow \alpha = 0 \\ V_o = 0 &\Rightarrow \alpha = 90^\circ \\ V_o = \frac{-2V_m}{\pi} &\Rightarrow \alpha = 180^\circ \end{aligned}$$



$$V_{\text{orms}} = \frac{V_m}{\sqrt{2}} \left[\pi + \frac{1}{2} \sin \omega t \right]^{1/2}$$

$$\Rightarrow \underline{I_{\text{orms}}} = \frac{V_{\text{orms}}}{R} = \frac{V_m}{\sqrt{2} \pi R} \left[\pi + \frac{1}{2} \sin \omega t \right]$$

* $0 - 90^\circ \rightarrow$ Rectifier function

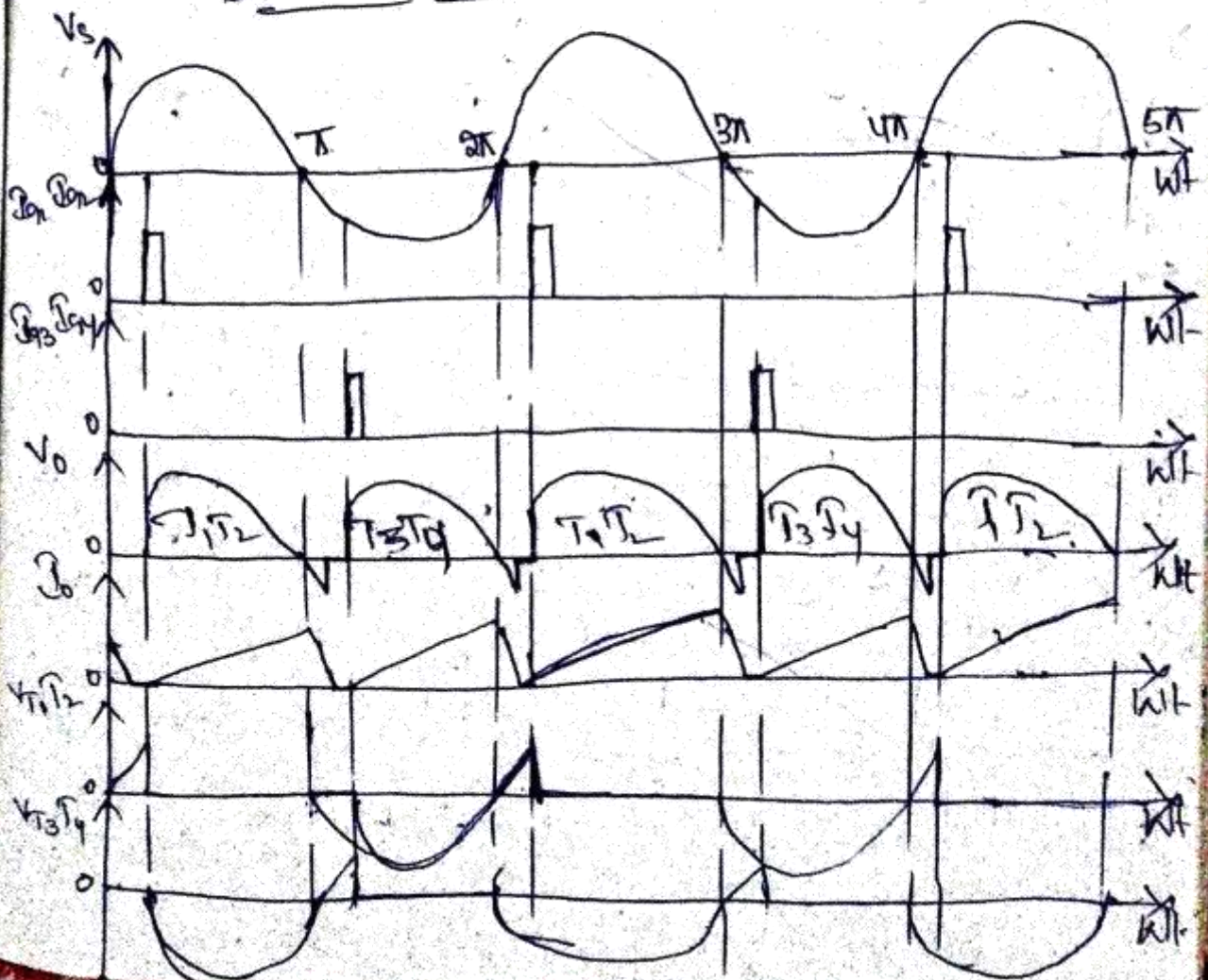
$90^\circ - 180^\circ \rightarrow$ Inverter function

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* 1- ϕ fully load Converter with R-L Load:

D.C.M :-

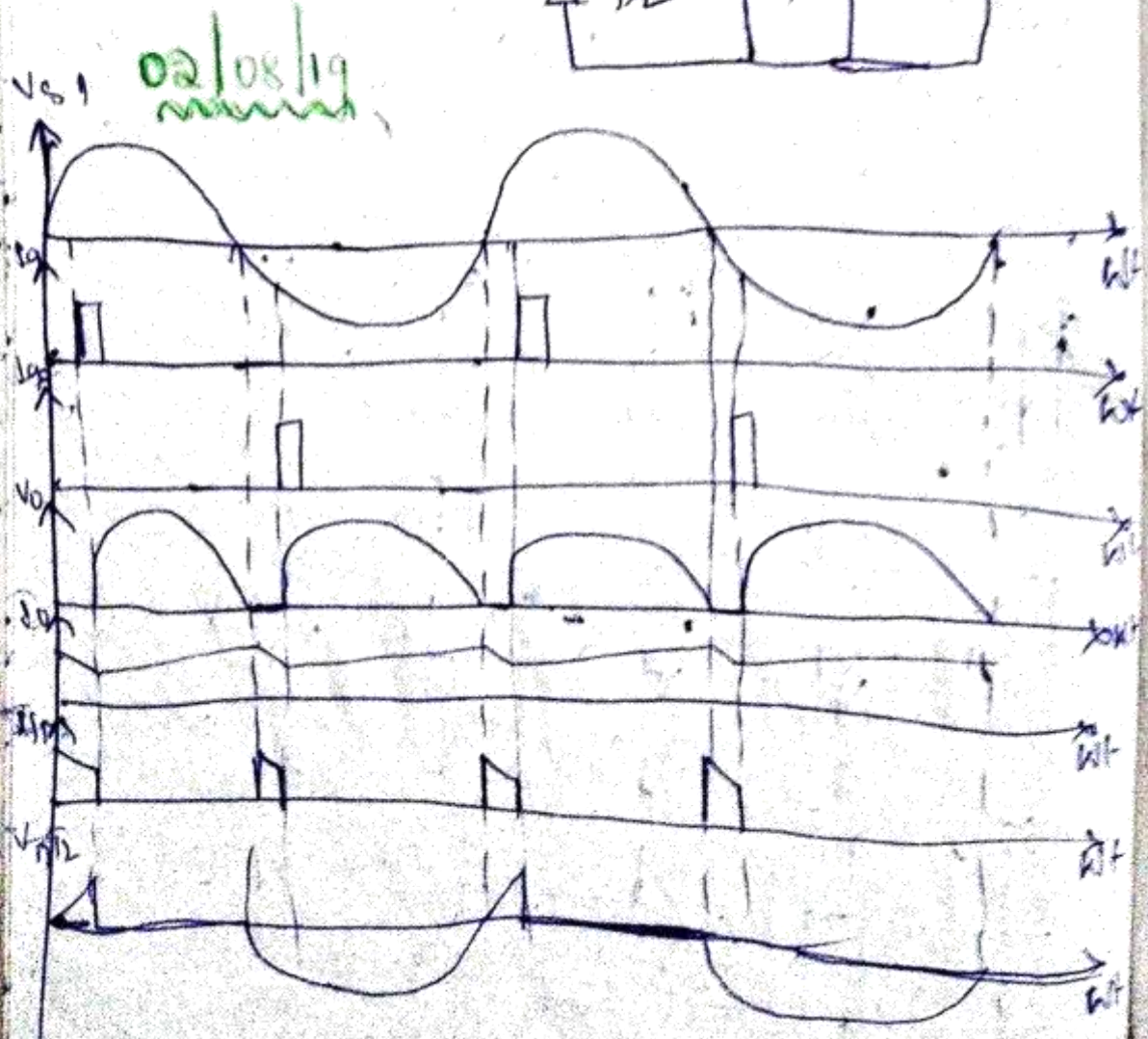
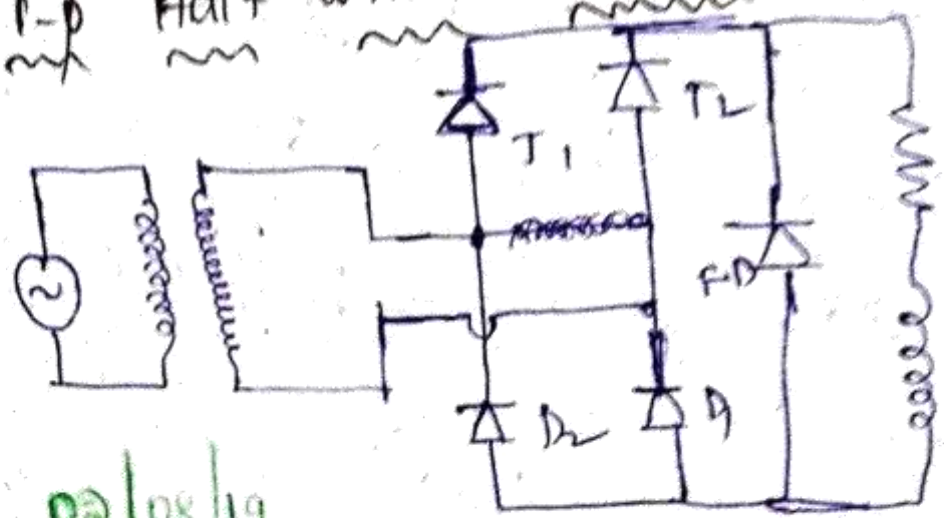
Some diagram



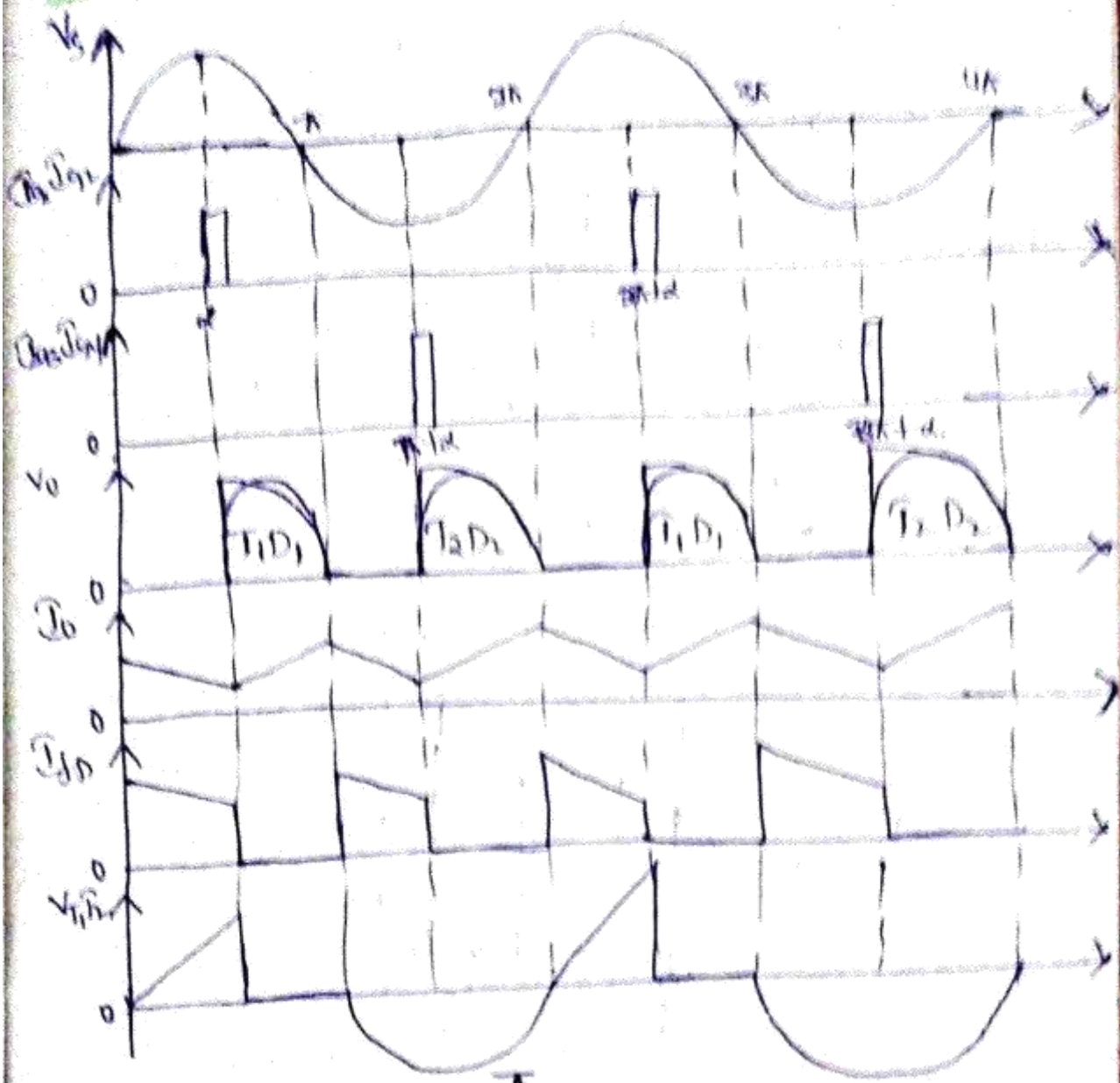
$$V_o = \frac{2}{\pi} \int_0^B V_m \sin \omega t \, d\omega t$$

$$V_o = \frac{V_m}{\pi} [\cos \alpha - \cos \beta]$$

* 1- ϕ Half Converter :-
Semiconductor



$\alpha = 90^\circ$



$$\Rightarrow V_0 = \frac{2}{2\pi} \int_{\alpha}^{\pi} V_m \sin \omega t \, dt$$

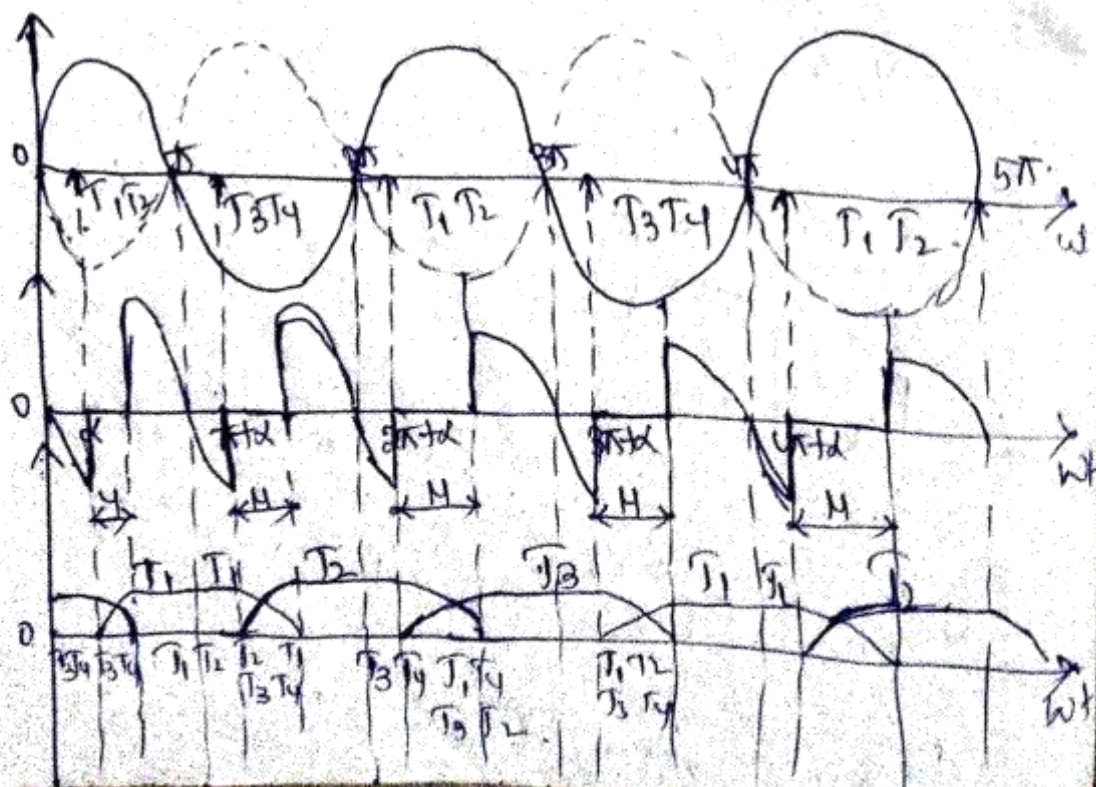
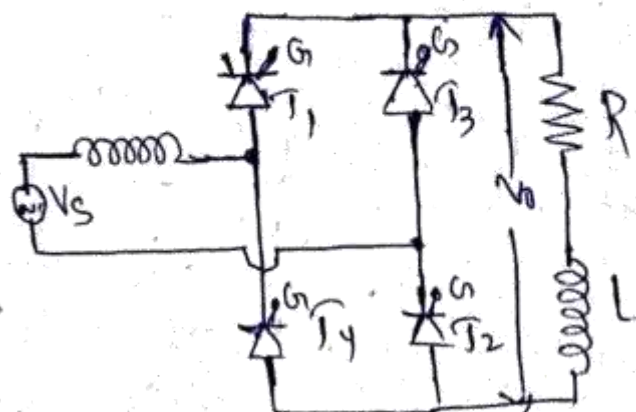
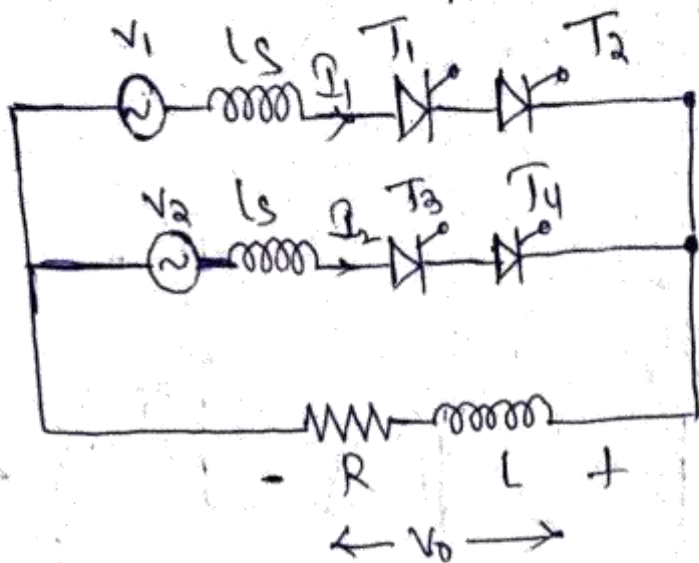
$$V_0 = \frac{V_m}{\pi} [1 + \cos \alpha]$$

$$\Rightarrow I_0 = \frac{V_0}{R} \Rightarrow \frac{V_m}{R\pi} [1 + \cos \alpha]$$

$$V_{\text{RMS}} = \frac{V_m}{\sqrt{2\pi}} \left[(\pi - \alpha) + \frac{1}{2} \sin 2\alpha \right]^{1/2}$$

$$P_{\text{RMS}} = \frac{V_m}{\sqrt{2} R \pi} \left[(\pi - \alpha) + \frac{1}{2} \sin 2\alpha \right]^{1/2}$$

* Effect of source of impedance on 1- ϕ full Converter with RL load:-



During the overlap angle μ for the loop abcd a.

$$V_1 - L_s \frac{di_1}{dt} = V_2 - L_s \frac{di_2}{dt}$$

$$V_1 - V_2 = L_s \left(\frac{di_1}{dt} - \frac{di_2}{dt} \right)$$

$$\therefore V_1 = V_m \sin \omega t, \quad V_2 = -V_m \sin \omega t$$

$$L_s \left(\frac{di_1}{dt} - \frac{di_2}{dt} \right) = 2V_m \sin \omega t \rightarrow (1)$$

As the load current is assumed constant throughout - $I_1 + I_2 = I_o$

Differentiation w.r.t "t".

$$\frac{di_1}{dt} + \frac{di_2}{dt} = 0 \rightarrow (2)$$

Adding Eqn (1) & (2) we get.

$$2V_m \sin \omega t \cdot \frac{di_1}{dt} = \frac{V_m}{L_s} \sin \omega t \rightarrow (3)$$

→ Load current I_1 through thyristor T_1 & T_2 bins 0 to $I_1 = I_o$. During overlap angle.

→ Now, At $\omega t = \alpha$, $i_1 = 0$ and at $\omega t = (\alpha + \mu)$, $i_1 = I_o$.

from Eqn (3)

$$\int_0^{i_1} di_1 = \frac{V_m}{L_s} \int_{\alpha/\omega}^{\alpha+\mu/\omega} \sin \omega t d\omega t$$

$$I_0 = \frac{V_m}{\omega L_s} \left[\cos \alpha - \cos(\alpha + \mu) \right] \rightarrow (4)$$

$$\Rightarrow \cos(\alpha + \mu) = \cos \alpha - \frac{\omega L_s}{V_m} \cdot I_0 \rightarrow (5)$$

* The o/p voltage V_o is "0 from α to $\alpha + \mu$ ".

* Thus the average o/p voltage V_{os} is given by

$$V_{os} = \frac{V_m}{\pi} \int_{\alpha + \mu}^{\alpha} \sin \omega t \, d\omega t$$

$$V_{os} = \frac{V_m}{\pi} \left[\cos(\alpha + \mu) - \cos(\pi + \alpha) \right]$$

$$V_{os} = \frac{V_m}{\pi} \left[\cos \alpha + \cos(\alpha + \mu) \right] \rightarrow (6)$$

The average value of o/p voltage at No load.

$$V_o = \frac{2V_m}{\pi} \cos \alpha$$

Maximum Mean o/p voltage.

$$V_{om} = \frac{2V_m}{\pi} \quad \text{When } \alpha = 0$$

Eqn (6) can be expressed as

$$V_{om} = \frac{\text{Mean o/p voltage}}{2} \left[\cos \alpha + \cos(\alpha + \mu) \right]$$

$$V_{or} = \frac{V_{om}}{2} [\cos \alpha + \cos(\alpha + \mu)] \rightarrow (7)$$

→ Substitute Eqn (5) in Eqn (6)

$$V_{or} = \frac{2V_{om}}{\pi} \cos \alpha - \frac{WLS}{\pi} \cdot I_0$$

$$= \frac{2V_{om}}{\pi} \cos \alpha - 2I_0 \rightarrow (8)$$

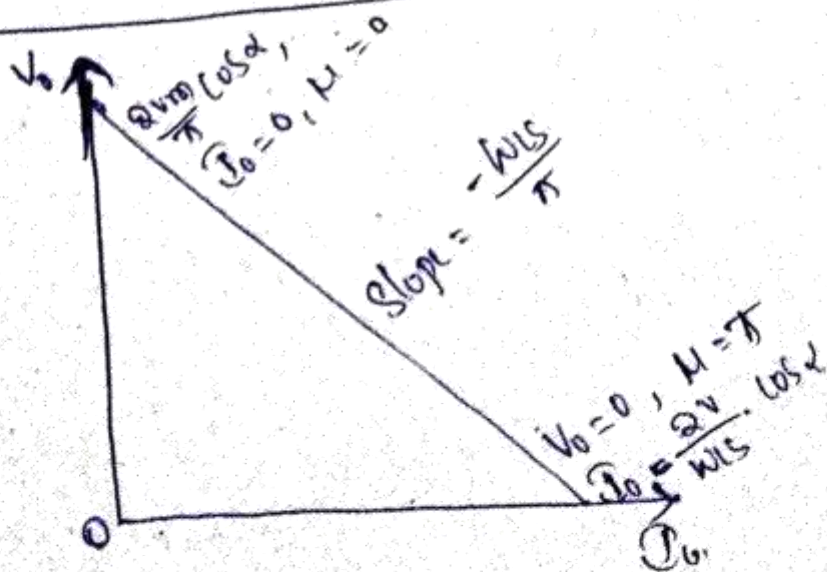
from Eqn (4) →

$$\cos \alpha = \frac{WLS}{V_{om}} \cdot I_0 + \cos(\alpha + \mu) \rightarrow (9)$$

from Eqn (9) in (8)

~~$$V_{or} = \frac{2V_{om}}{\pi} \left[\frac{WLS}{V_{om}} \cdot I_0 + \cos(\alpha + \mu) \right] - 2I_0$$~~

$$V_{or} = \frac{2V_{om}}{\pi} \cos(\alpha + \mu) + \frac{WLS}{\pi} \cdot I_0 \rightarrow (10)$$

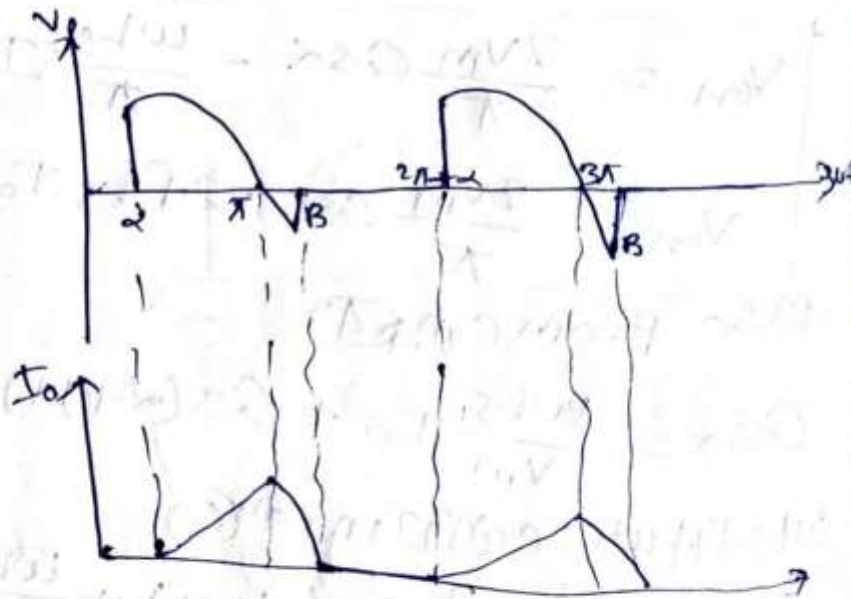
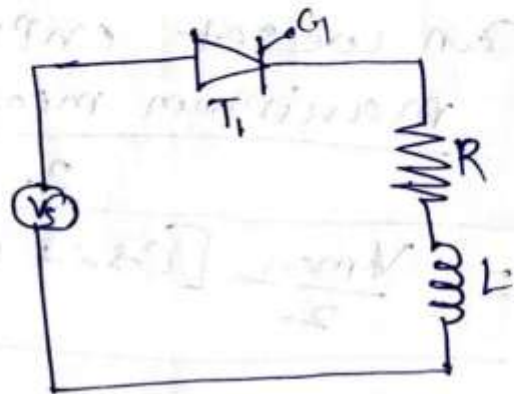


Problems

Q.1) $V_s = 230V, 50Hz, \pm Pulse$ SCR Controlled Converter is triggered at $\alpha = 40^\circ$ and the load current and it needs to be at an angle of 210° . Find the circuit turn off time, calculate the average voltage, average load current
 $R = 5\Omega, L = 2mH$

Given data:-

- $V_s = 230V$
- $F = 50Hz$
- $\alpha = 40^\circ$
- $\beta = 210^\circ$
- $R = 5\Omega$
- $L = 2mH$
- $t_c = ?$
- $V_o = ?$
- $I_o = ?$



From this wave waveform

$$\omega t = 2\pi - \beta$$

$$t_c = \frac{2\pi - \beta}{\omega}$$

$$\begin{aligned} \text{(i)} \quad t_c &= \frac{360 - 210}{2\pi \times 50} \\ &= 8.33 \text{ msec} \end{aligned}$$

$$\text{(ii)} \quad V_o = \frac{V_m}{2\pi} (\cos \alpha - \cos \beta)$$

$$V_o = \frac{\sqrt{2} \times 230}{2\pi} (\cos 40^\circ - \cos 210^\circ) = \frac{\sqrt{2} \times 230}{2\pi} (\cos 40^\circ - \cos 210^\circ)$$

$$V_o = 8A \cdot 46V$$

(ii) Average Load current

$$I_0 = \frac{V_0}{R} = \frac{84.48}{5} = 16.89 \text{ A}$$

A 1- ϕ 230V, 1KW heater is connected across 230V 1- ϕ supply, 50Hz, 2- ϕ SCR Through an SCR, two observe in the β . firing angle delay of 45° and 90° . Calculate of power

Given data:-
heater:-

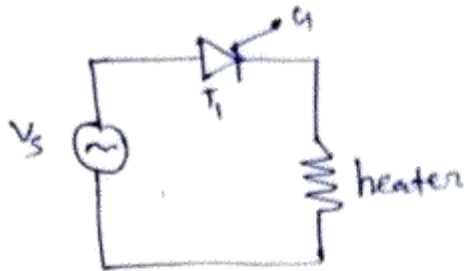
$$V = 230 \text{ V}$$

$$P = 1 \text{ kW}$$

$$\alpha = 45^\circ$$

$$= 90^\circ$$

$$f = 50 \text{ Hz}$$



Power observed by the heater

= RMS output voltage \times RMS output current

$$P_0 = V_{\text{rms}} \times I_{\text{rms}} \quad \left(I_{\text{rms}} = \frac{V_{\text{rms}}}{R} \right)$$

$$P = \frac{(V_{\text{rms}})^2}{R}$$

$$\text{Heater resistance } (R) = \frac{V^2}{P} = \frac{(230)^2}{1000} = 52.9 \Omega$$

$$i) V_{0 \text{ rms}} = \frac{\sqrt{2} \times V_s}{2\sqrt{\pi}} \left[(\pi - \alpha) + \frac{1}{2} \sin 2\alpha \right]^{1/2}$$

$$\text{Case-1 } \alpha = 45^\circ$$

$$= \frac{\sqrt{2} \times 230}{2\sqrt{\pi}} \left[(\pi - 45^\circ) + \frac{1}{2} \sin 2(45^\circ) \right]^{1/2} \times \frac{\pi}{180}$$

$$= 155.07 \text{ V}$$

$$\text{Heater resistance } (R) = \frac{V_{\text{rms}}^2}{P} = \frac{(155.07)^2}{1000} = 24.04 \Omega$$

$$\text{Case-ii } \alpha = 90^\circ$$

$$= \frac{\sqrt{2} \times 230}{2\sqrt{\pi}} \left[(\pi - \pi/2) + \frac{1}{2} \sin(2 \times 90^\circ) \right]^{1/2}$$

$$= 115 \text{ V}$$

$$\text{Heater resistance } (R) = \frac{V_{\text{rms}}^2}{P} = \frac{115^2}{1000} = 24.025 \Omega$$